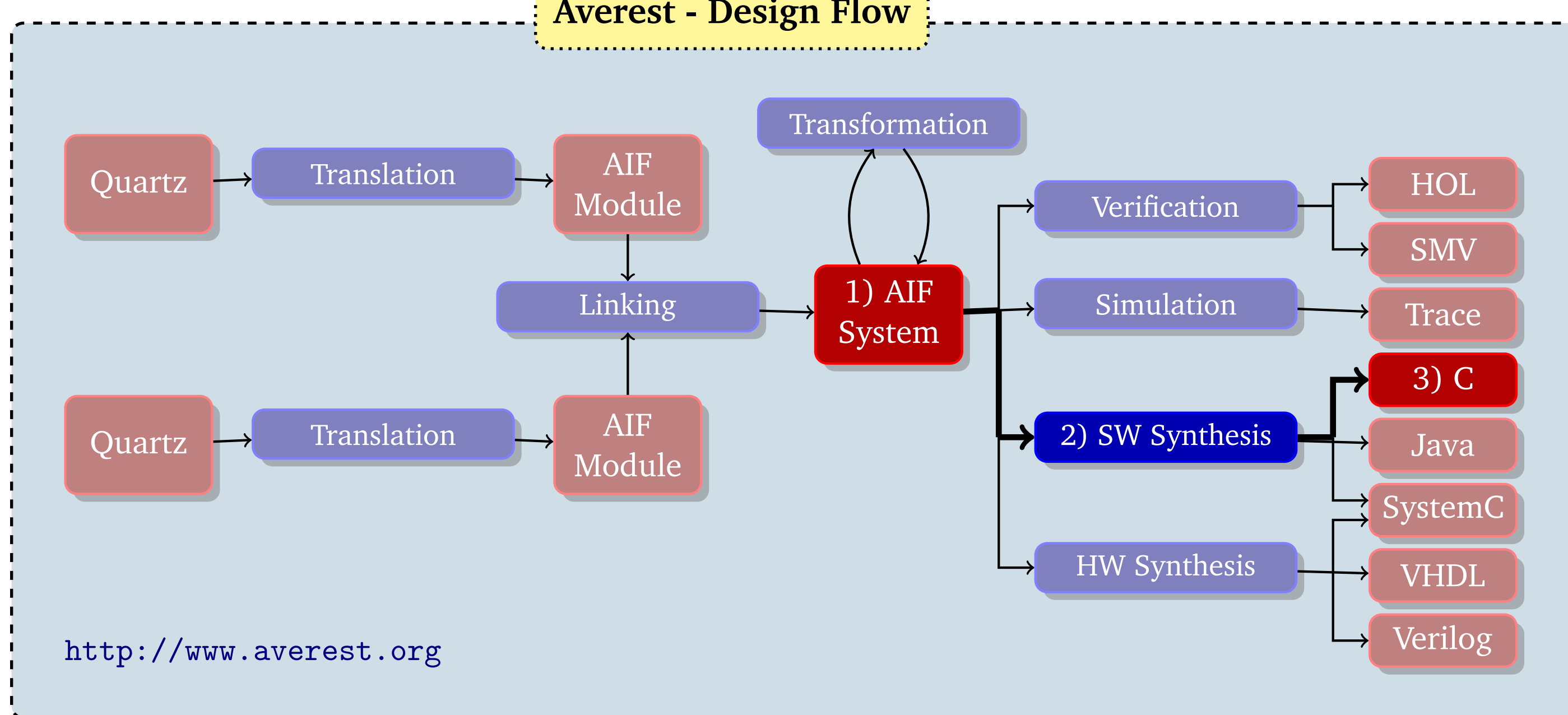


Multithreaded Code from Synchronous Programs: Extracting Independent Threads for OpenMP

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Averest - Design Flow



<http://www.averest.org>

1) AIF System

1.1) AIF System

Interface:
Inputs: $start$
Output: z_1, z_2
Locals: x_1, x_2, y_1, y_2
Guarded Actions:
 $start \Rightarrow l_1 = true$
 $l_1 \Rightarrow next(l_1) = true$
 $l_1 \Rightarrow x_1 = true$
 $l_1 \Rightarrow x_2 = true$
 $l_1 \wedge x_1 \Rightarrow y_1 = true$
 $l_1 \wedge x_2 \Rightarrow y_2 = true$
 $l_1 \wedge \neg x_2 \Rightarrow z_1 = true$
 $l_1 \wedge y_1 \wedge x_2 \Rightarrow z_1 = true$
 $l_1 \wedge y_1 \wedge y_2 \Rightarrow z_2 = true$

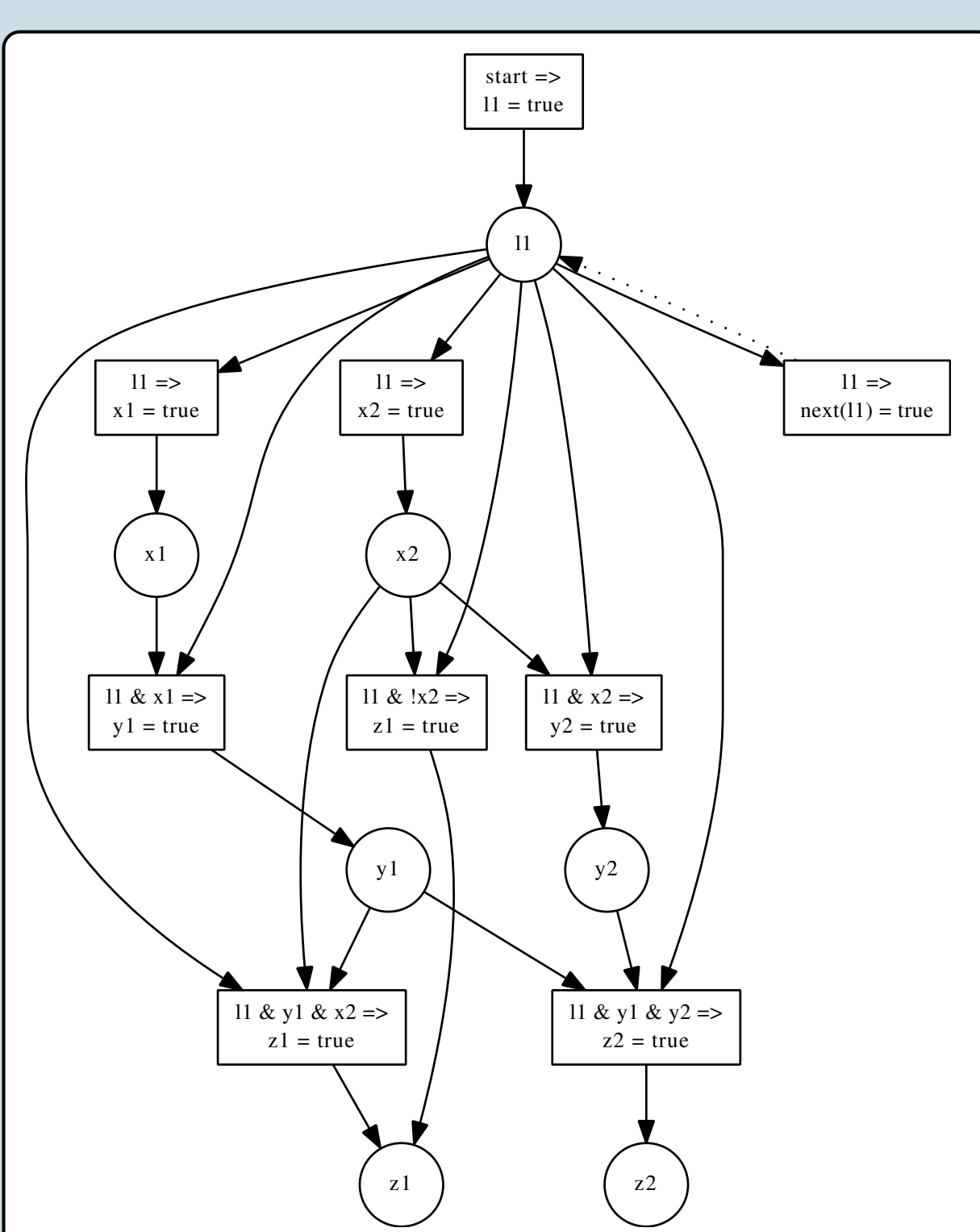
Behavior similar to a (clocked) sequential circuit.
 Each clock:

1. read inputs,
2. execute all actions,
3. write outputs.

Execution of actions in software:

- theoretically: concurrently, in zero time
- practically: find a sequence.

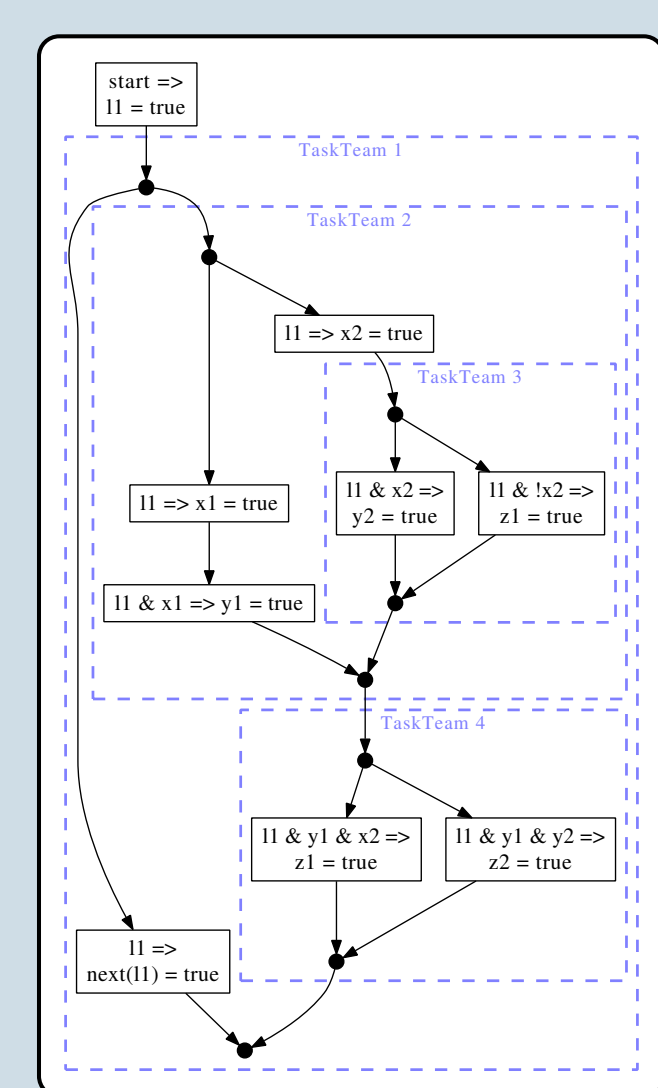
1.2) Action Dependency Graph (ADG)



- partial ordering over guarded actions
- required to sequentialize execution

2) Software Synthesis

2.2b) Interleaved Dependencies



OpenMP does not support interleaved dependencies. Can be handled by

- Duplicating actions (as shown in 2.2a))
- Moving up the barrier (as shown in figure above)

2.1) Translation to Task Structure

Idea: Split dependency graph vertically and create group of actions such that each group can be executed as a single thread. The created groups must not communicate within a single macro step.

Definition of Task Structure:

- TaskAction ::= $\gamma \Rightarrow A \mid \text{TaskTeam}$
- TaskTeam ::= (Task TaskTeam) \mid Task
- Task ::= (TaskAction Task) \mid TaskAction
- TaskStructure ::= Task

Translation of ADG to Task Structure:

- A set of open tasks marks potential places, where actions can be appended.
- Determine all actions that can fire and schedule them to the open tasks. Synchronization may be required.

(See paper for a detailed description.)

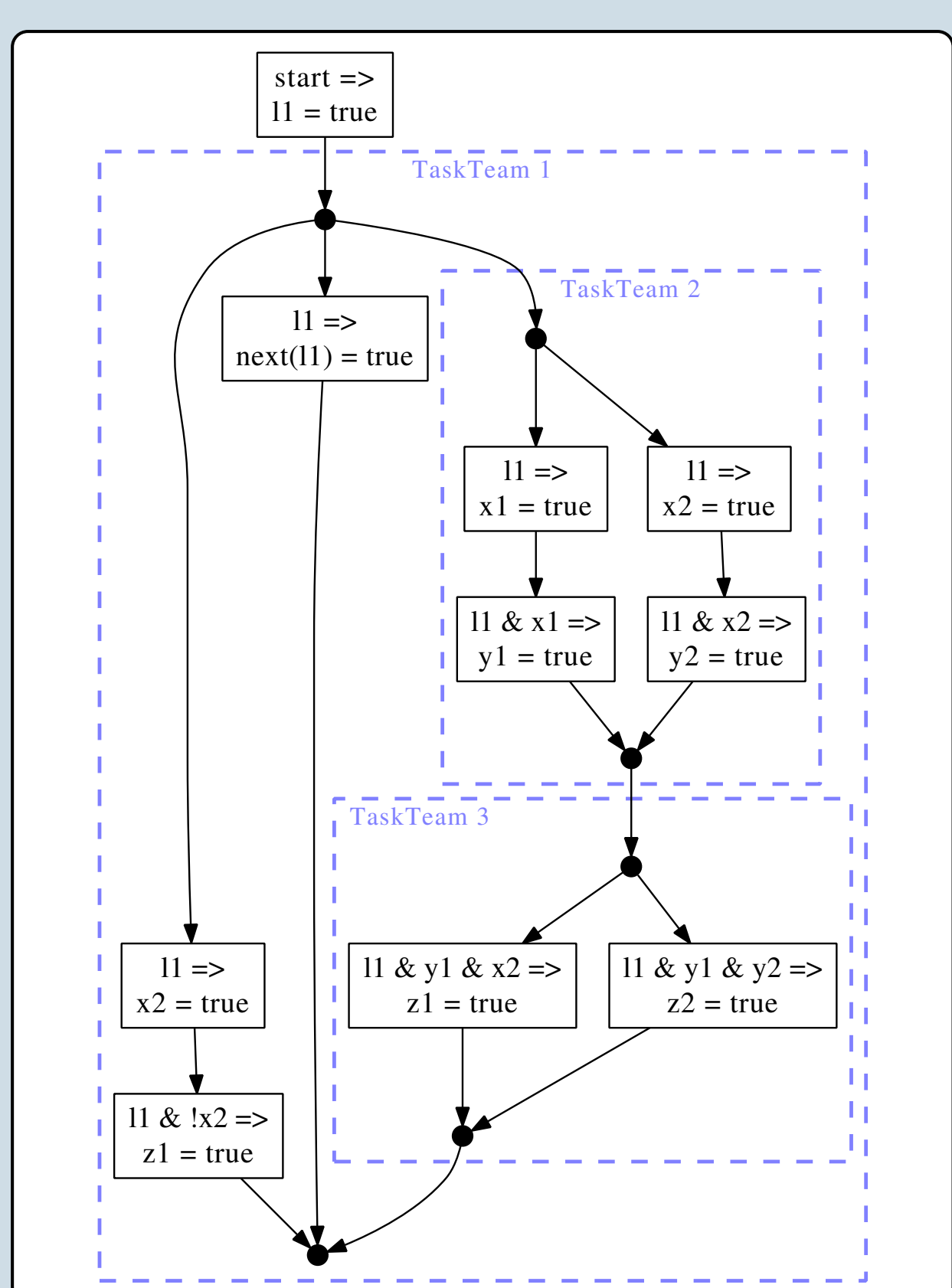
3) Multi-Threaded C

3) Generating C Code using OpenMP

```
bool start, l1, _next_l1, x1, x2, y1, y2, z1, z2;
while(true) {
    // read inputs
    read(start);
    // execute actions
    if(start) l1=true;
    #pragma omp parallel sections \
        reduction(=:x2) reduction(=:z1) {
        #pragma omp section
        { if(l1) _next_l1 = CO; }
        #pragma omp section
        { if(l1) x2 = B(); if(l1 && !x2) z1 = F(); }
        #pragma omp parallel sections {
            #pragma omp section
            { if(l1) x1 = A(); if(l1 && x1) y1 = D(); }
            #pragma omp section
            { if(l1) x2 = B(); if(l1 && x2) y2 = E(); }
        }
        #pragma omp parallel sections {
            #pragma omp section
            { if(l1 && y1 && x2) z1 = G(); }
            #pragma omp section
            { if(l1 && y1 && y2) z2 = H(); }
        }
    }
    // write outputs
    write(z1);
    write(z2);
}
```

- Each task team represents a fork and is translated using the `sections` directive.
- Each task in a task team is translated as a thread using the `section` directive.
- Each task action can be translated as a conditional C statement

2.2a) Task Structure



Each task team contains a list of tasks. Each task can be a sequence of actions or a task team. The begin (end) of a task team represents a fork (join) of the given set of tasks.

Alternative: Pipelining Approach

Basic Idea: Partition system into stages, i.e. split ADG "horizontally" instead of "vertically".
 => "Multithreaded Code from Synchronous Programs: Generating Software Pipelines for OpenMP" (MBMV'10)